

CZUJNIK WIZYJNY DATAVS2 AOR

DATAVS2-06DEAOR

Czujnik wizyjny, 6mm obiektyw, AOR, Czerwone LED

- Dopasowanie wzorca w obrębie 360°
- 8 różnych typów kontroli
- Pamięć na 20 inspekcji
- Funkcje logiczne, 4 wyjścia



OPIS PRODUKTU

DataVS2 firmy Datalogic to seria czujników wizyjnych przeznaczonych do zastosowania w aplikacjach maszynowych. Czujniki wyposażone w optykę, diodę LED i elektronikę są zamknięte w kompaktowej obudowie. Parametry pomiaru są ustawiane za pomocą komputera poprzez złącze Ethernet. Oprogramowanie jest dołączone wraz z sensorem a proces ustawiania parametrów jest prosty i intuicyjny. Seria DataVS2 jest dostępna w 4 różnych wersjach z różnymi typami kontroli.

Zawansowany system rozpoznania obiektu AOR - Posiada typ kontroli rozpoznania obiektu w 360°.

Funkcje logiczne łączące różne typy kontroli i wyjścia takie jak: AND, OR, NOT, NAND, NOR itp..



DANE TECHNICZNE

Napięcie zasilania	24 V DC ±10 %
Tętnienia	1Vpp maks. z iluminatorem 2Vpp bez iluminatora
Pobór prądu	100 mA at 24 VDC (bez iluminatora)
Wyjście	4 PNP
Prąd wyjściowy	100 mA maks.
Rozdzielczość	640x480 (VGA)
Interfejs sieciowy	Złącze M12 4-pinowe Ethernet 10/100 Mbs
Interfejs zewnętrzny iluminatora	Sygnal strobulujący(24 V PNP N.O)
Częstotliwość wyświetlania klatek	60 fps
Obiektyw	Zintegrowany (6 mm/8 mm/12 mm/16 mm)

Wskazanie	4 LED
Połączenie	Złącze M12 8-pinowe A-kodowane Złącze M12 4-pinowe D-kodowane
Stopień ochrony	IP50
Materiał obudowy	Stop aluminium/ABS
Masa	125 g
Temperatura pracy	od -10 do +50 °C
Temperatura przechowywania	od -25 do +70 °C

TYPY KONTROLI



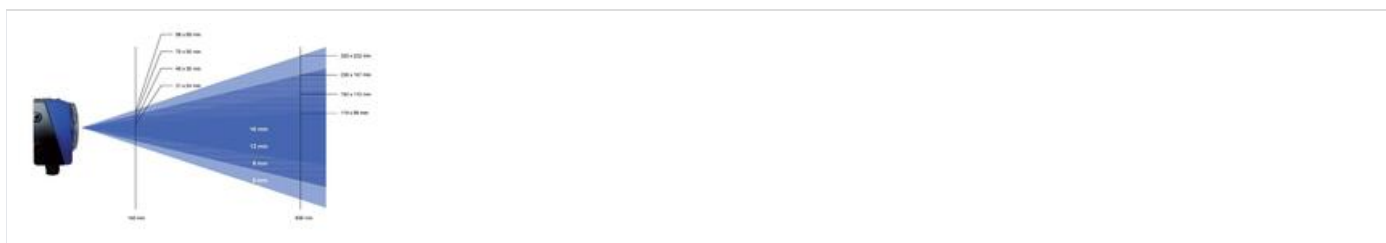
Control	Function	Applications	Image
Pattern Match	Search for a sample within a specified range	<ul style="list-style-type: none"> • Packaging: check of logo • Installation: product-orientation • Automation of post: stamp control 	
Contour Match	Control of form	<ul style="list-style-type: none"> • Metal working: integrity check • Foodstuffs: control of form 	
Position	Control of limit position of the object	<ul style="list-style-type: none"> • Bottling: level control • Foodstuffs: control of label position 	
Width	Measures the object's width	<ul style="list-style-type: none"> • Installation: control of plastic parts • Woodworking industry: measurement of branch thickness 	
Counting	Counts number of objects along a line	<ul style="list-style-type: none"> • Electronics: counting components • Pharmaceutical industry: Counting units 	

Contrast	Calculation of contrast	<ul style="list-style-type: none"> • Foodstuffs: checking presence of date and consignment label • Metal working: Check of laser marking 	
Brightness	Calculation of luminance	<ul style="list-style-type: none"> • Bottling: checking presence of cap • Packaging: counting objects 	

ZAKRES POMIAROWY

Obszar pomiaru

Odległość (mm)	Obszar pomiaru (Szerokość x Wysokość) w mm			
	DATAVS2-16-DE-xxx	DATAVS2-12-DE-xxx	DATAVS2-08-DE-xxx	DATAVS2-06-DE-xxx
50	-	17 x 12	25 x 20	42 x 30
80	-	25 x 20	40 x 30	60 x 41
110	-	33 x 25	55 x 40	80 x 55
140	31 x 24	45 x 35	70 x 50	98 x 69
170	39 x 29	53 x 38	85 x 60	118 x 83
200	46 x 34	60 x 50	100 x 70	138 x 92
300	70 x 53	90 x 65	145 x 103	201 x 140
400	94 x 71	121 x 82	186 x 132	265 x 189
500	118 x 89	150 x 110	236 x 167	330 x 232
600	143 x 107	185 x 130	282 x 232	385 x 270



WYMIARY

Min. temperatura pracy	-10 °C
Pobór mocy (max)	0,1 A
Podłączenie elektryczne	Złącze M12 4-pinowe kodowanie D, Złącze M12 8-pinowe
Prąd wyjściowy max.	0,1 A
Stopień ochrony IP	IP50
Tolerancja napięcia	10%
Wyjście	4x PNP

The Advanced Object Recognition (AOR) models integrate new important functionalities, including:



360° Pattern Match Locator
Object detection independent from rotations.



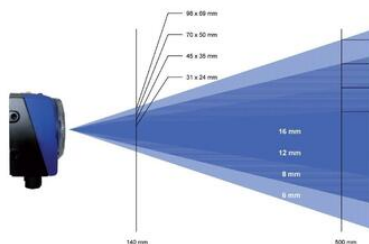
Logical tools
Possibility to combine the results of the single tools through boolean operator (AND, OR, NOT, etc.)



Advanced Ethernet
Current inspection results available also on Ethernet communication.



Speed-up
High execution speed thanks to the management of reduced resolution and TURBO mode.



360° Pattern match

The Advanced Object Recognition (AOR) models include all the controls and locators available on Object Recognition models as well as the new 360° Geometric Pattern Match Locator.



- Step 1: Image Setup**
The first step consists in connecting the sensor and configuring the image quality parameters. When the desired results are obtained, the user can memorize the image that will be used as a template during sensor functioning.
- Step 2: Teach**
The second step establishes the acceptance criteria to distinguish objects from wastes. One or more controls can be selected according to the task to carry-out.
- Step 3: Run**
The third step configures the sensor digital outputs, simulates sensor functioning on the PC to verify the controls chosen and activates the operating phase on the sensor using the PC only to control the diagnostics.



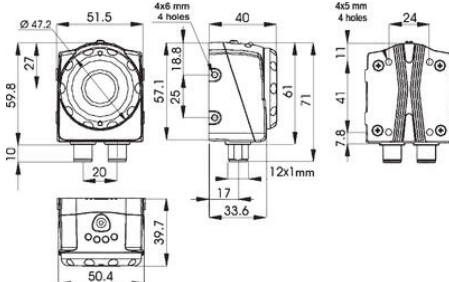
M12 4-pole Ethernet

PIN 1 = white/orange = RX+
PIN 2 = white/green = TX+
PIN 3 = orange = RX-
PIN 4 = green = TX-



M12 8-pole (power supply and I/O)

PIN 1 = white = digital input 1
PIN 2 = brown = 24 Vdc
PIN 3 = green = STROBE for external illuminator
PIN 4 = yellow = output 1
PIN 5 = grey = output 2
PIN 6 = pink = output 3
PIN 7 = blue = GND
PIN 8 = red = external trigger



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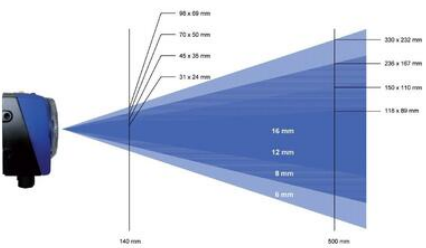
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